

# (In)Efficiency and Reasonable Cost Models

Beniamino Accattoli

INRIA & École Polytechnique

# Once Upon a Time

At the **beginning of CS** different models were proposed:

Church's  $\lambda$ -calculus;

Godel's partial recursive functions;

Turing's machines (TM);

...

**Church-Turing Thesis**: all models are equivalent.

# The Models Farm

All models of **effective calculability** are equivalent but...

Some models are **more equivalent** than others.

Church himself found **TM** more effective than  **$\lambda$ -calculus**.

In which sense **TM** are more effective than  **$\lambda$ -calculus**?

Contemporary Perspective:

The **cost models** of  $\lambda$ -calculus are **unclear**.

# Turing Machines

Turing machines are effective because of **self-evident** cost models:

**Time**: number of machine transitions;

**Space**: maximum number of used cells on the tape;

**Complexity theory** is based on Turing machines.

# Reasonable Computational Model

A computational model  $X$  is

reasonable

when  $X$  and TM can simulate each other  
with polynomially bounded overhead in time  
(with respect to their time cost models)

**Effective** Church-Turing Thesis: all models are reasonable.

(alternatively called *extended*, *efficient*, *modern*, or *complexity-theoretic* thesis)

**Example:** Random Access Machines (RAM) are reasonable.

# Effective Thesis and Complexity theory

Consequence of the effective thesis:

(Super)-polynomial classes (e.g. P or NP) are model-independent.

Sub-polynomial time is not stable by changing the model.

Founding fathers' skepticism, revisited:

Is the  $\lambda$ -calculus a reasonable computational model?

Is there a cost model that makes  $\lambda$ -calculus reasonable?

# $\lambda$ -Calculus

Natural **cost models** for the  $\lambda$ -calculus:

**Time**: number of  $\beta$ -steps;

**Space**: maximum size of a term during evaluation;

Something is **wrong** with this naive approach.

# This Talk

Explaining the **subtleties** of **time** cost models for the  $\lambda$ -calculus.

Focussing on:

the **unavoidable** nature of the problem.

**efficient** vs **reasonable** strategies.



# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# $\lambda$ -Calculus

Language:

$$t, u, s \quad := \quad x \quad | \quad \lambda x.t \quad | \quad tu$$

$\beta$ -Reduction:

$$\frac{}{(\lambda x.t)u \rightarrow_{\beta} t\{x \leftarrow u\}} \text{ (root } \beta)$$

$$\frac{t \rightarrow_{\beta} u}{ts \rightarrow_{\beta} us} \text{ (@l)}$$

$$\frac{t \rightarrow_{\beta} u}{\lambda x.t \rightarrow_{\beta} \lambda x.u} \text{ } (\lambda)$$

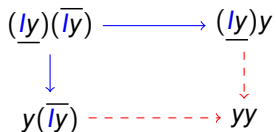
$$\frac{t \rightarrow_{\beta} u}{st \rightarrow_{\beta} su} \text{ (@r)}$$

# Confluence

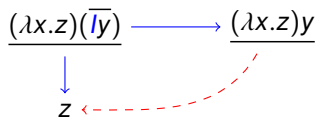
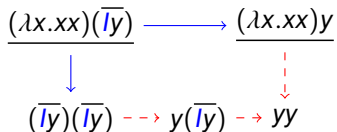
$\rightarrow_\beta$  is **non-deterministic** but confluent.

Let  $I := \lambda z.z$ . Simplest redex  $Iy \rightarrow_\beta y$ .

Confluence diagrams 1, **independent** redexes:



Confluence diagrams 2 and 3, **duplication** and **erasure**:



## Two Main Issues

Two main issues with reasonable time cost models:

The choice of the evaluation **strategy**.

The (**non-**)**atomicity** of  $\beta$ -reduction.

## A first Look at the Strategy Issue

**Confluence** = all strategies compute the **same** result.

Some strategies may **terminate** while other **diverge**.

Intuition says that **reasonable** strategy = **efficient** strategy.

In particular one expects:

A reasonable strategy to be **terminating**;

A reasonable strategy to take **not too many steps**.

Both points are **misleading**!

# Atomicity

At first sight, the **strategy** issue seems more relevant.

But the real issue is the **non-atomicity** of  $\beta$ -reduction.

Non-atomicity materializes as the **size explosion** problem.

**Size explosion:**

subtle problem, surprisingly **neglected** by the literature.

# Outline

Introducing  $\lambda$ -Calculi

**The Structure of the Problem**

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# Higher-Order vs First Order

Two views on computation:

**First-Order**: programs acting on **numbers**, strings, etc;

**Higher-Order**: programs acting on **programs**.

Turing Machines are **first-order**.

$\lambda$ -calculus models **higher-order** computation.

**Expected**: higher-order reasonably simulates first-order.

**Unclear**: does first-order reasonably simulate higher-order?



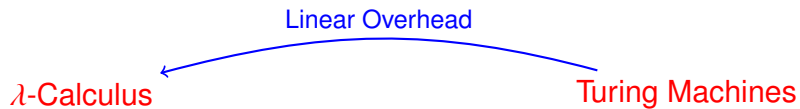
# Bird's Eye View

$\lambda$ -Calculus

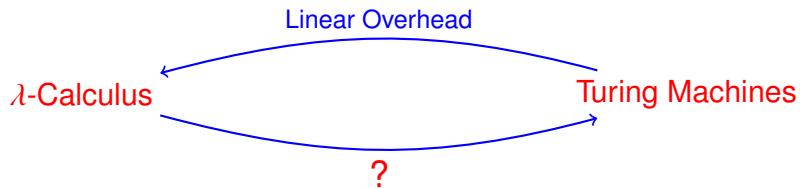
?

Turing Machines

# Bird's Eye View



# Bird's Eye View



# Bird's Eye View



## $\beta$ -Reduction is Reasonable, Indeed

It turns out that size explosion is **circumventable**.

The **number** of  $\beta$ -steps  
is  
a **reasonable** time cost model.

**First result** in a special case in 1995 by **Blelloch** and **Greiner**.

**General result** in 2014 by **Accattoli** and **Dal Lago**.

# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

**The Deterministic  $\lambda$ -Calculus**

Introducing Size Explosion

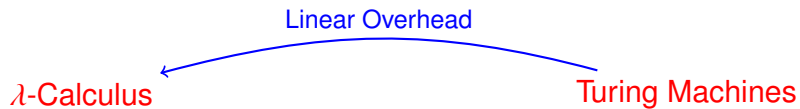
Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# Bird's Eye View



# From TM to $\lambda$ -Calculus

First simulation TM  $\rightarrow$   $\lambda$ -calculus in 1936 (Turing).

Nowadays, **disappeared** from the literature

(that rather shows the simulation **partial recursive functions**  $\rightarrow$   $\lambda$ -calculus).

TM  $\rightarrow$   $\lambda$ -calculus is the **easy** direction, and yet **subtle**.

TM can be represented on a **tiny fragment** of the  $\lambda$ -calculus.

So tiny, that the strategy problem **disappears**.



# A Simulation Stronger Than It Seems

$\lambda$ -calculus simulates TMs with **linear** overhead.

The result is due to **Ugo Dal Lago**.

It is part of Accattoli & Dal Lago in **RTA 2012**, in the Appendix.

At the time, we did **not** pay attention to this **very strong** fact.

I reworked the simulation, there is a note on my webpage.

# The Deterministic $\lambda$ -Calculus

$\Lambda_{\text{det}}$  is given by the following **restricted** language:

$$\begin{aligned} t, u, s & ::= x \mid \lambda x.t \mid tv \\ v & ::= x \mid \lambda x.t \end{aligned}$$

endowed with **weak** evaluation (CbN and CbV coincide):

$$\frac{}{(\lambda x.t)v \rightarrow_{wh} t\{x \leftarrow v\}} \text{ (root } \beta) \qquad \frac{t \rightarrow_{wh} u}{ts \rightarrow_{wh} us} \text{ (@l)}$$

In  $\Lambda_{\text{det}}$ ,  $\beta$ -reduction is **deterministic**.

$\Lambda_{\text{det}}$  is the intersection of the **weak** and the **CPS**  $\lambda$ -calculi.

## Perpetual Weak Strategies can be Reasonable (!)

Closed  $\Lambda_{\text{det}}$  simulates TMs with **linear** overhead.

In  $\Lambda_{\text{det}}$  all weak strategies **collapse**.

Therefore, **every** weak strategy simulates TMs efficiently.

Every weak strategy with polynomial overhead is **reasonable**.

Even if it is **perpetual** (*i.e.* it diverges as soon as possible)!

A reasonable strategy needs **not** to be **terminating!!!**

# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

**Introducing Size Explosion**

Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# Bird's Eye View

$\lambda$ -Calculus

Turing Machines



Size Explosion Problem

## Warming Up

Let  $\delta$  be the **duplicator** combinator, *i.e.*  $\delta := \lambda x.xx$ .

Famous divergent term  $\Omega := \delta\delta = (\lambda x.xx)\delta \rightarrow_{\beta} \delta\delta$ .

So, **infinite** iterated duplications:  $\Omega \rightarrow_{\beta} \Omega \rightarrow_{\beta} \dots$

**Trivial fact:** time complexity  $\geq$  space complexity.

## Size Explosion — Example

$$t_0 := y \text{ and } t_n := \delta t_{n-1}, \text{ or } t_n := \underbrace{\delta(\delta(\delta \dots (\delta y) \dots))}_{n \text{ times}}.$$

$$t_1 = \delta y = (\lambda x. xx)y \rightarrow_{\beta} yy$$

$$t_2 = \delta t_1 \rightarrow_{\beta} \delta(yy) \rightarrow_{\beta} (yy)(yy)$$

$$t_3 = \delta t_2 \rightarrow_{\beta} \delta((yy)(yy)) \rightarrow_{\beta} ((yy)(yy))((yy)(yy))$$

...

$$t_n \rightarrow_{\beta}^n y^{2^n}$$

### Size-Explosion:

The size  $|t_n|$  of the initial term is **linear** in  $n$ ;

The number of steps  $\rightarrow_{\beta}^n$  is **linear** in  $n$ ;

The size  $|y^{2^n}|$  of the final term is **exponential** in  $n$ .

## Size Explosion — The Moral

Time complexity = number of  $\beta$ -steps?

Size-explosion suggests **no**:

Number of  $\beta$ -steps  
does **not** even account for the time  
to **write down the result**.



# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

**Size Explosion is Everywhere**

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# Is It the Strategy?

$\lambda$ -calculus is **non-deterministic** but **confluent**.

Different **strategies** have very different evaluation **lengths**.

Does **size explosion** depend on the evaluation **strategy**?

**No**, all strategies suffer from size explosion.

## Back to the Atomicity of $\beta$

There is an **exploding family** in the **deterministic**  $\lambda$ -calculus  $\Lambda_{\text{det}}$ .

In  $\Lambda_{\text{det}}$ , all strategies **collapse**.

Therefore,

**No** strategy  
is immune from  
**size explosion**.

# Size Explosion — Worst Case Ever

Consider:

$$s_1 := \lambda x. \lambda y. (yxx)$$

$$s_1 I = (\lambda x. \lambda y. (yxx)) I \rightarrow_{\beta} \lambda y. (yII) = r_1$$

Define the following families of terms  $s_n$  and **exploding results**  $r_n$ :

$$s_{n+1} := \lambda x. (s_n(\lambda y. (yxx))) \qquad r_{n+1} := \lambda y. (y r_n r_n)$$

Note that  $|s_n| = O(n)$  and  $|r_n| = \Omega(2^n)$ .

**Size Explosion:**  $s_n I \rightarrow_{\beta}^n r_n$ .

**Key property:**

$$s_{n+1} r_m \rightarrow_{\beta} s_n (\lambda y. (y r_m r_m)) = s_n r_{m+1}$$

# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

Size Explosion is Everywhere

**$\lambda$ -Calculi are Reasonable**

Unfolding and Reasonable Representations

Efficiency and Reasonable Cost Models

# $\lambda$ -Calculus

Natural **cost models** for the  $\lambda$ -calculus:

**Time**: number of  $\beta$ -steps;

**Space**: maximum size of a term during evaluation;

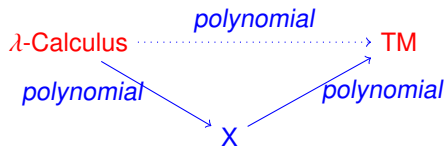
**Problem**: size explosion.

It looks like the problem is about **time**.

In fact, it is the other way around... the problem is about **space**.

**Hidden wrong assumption**: space = size of the term.

# How to Stop Worrying and Love the Bomb



Introduce an intermediate system  $X$ ;

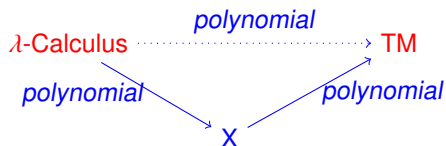
$X$  simulates  $\lambda$ -calculus up to some form of sharing;

$X$  computes a compact representation of the result;

Avoiding size-explosion.

In the best cases the polynomials are linear.

# Decomposing the $\lambda$ -Calculus



In the literature there are 3 instances for  $X$ :

Graph Rewriting (e.g. **Proof Nets**);

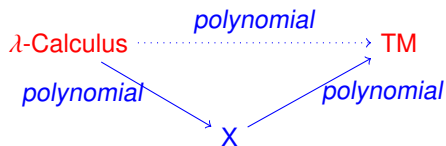
Explicit Substitutions (aka **let** expressions);

Abstract Machines.

Fixed  $X$ , the details also depend much on  $\lambda$ -dialect under study.



# Complexity of a Strategy



Fix a **strategy**  $\rightsquigarrow$  and an **evaluation**  $t_0 \rightsquigarrow^n u$ .

**Implementation** in  $X$ :  $t_0 \rightsquigarrow^n u$  iff  $s_{t_0} \rightsquigarrow_X^* s'$  with  $\underline{s'} = u$ .

**Complexity** of  $\rightsquigarrow =$  **cost** of implementing  $\rightsquigarrow$  in  $X$  with  $\rightsquigarrow_X$ , wrt:

1. **Input**: size  $|t_0|$  of the initial term.
2. **Strategy**: # of  $\beta$ -steps  $n$ .

$\rightsquigarrow$  is a **reasonable** strategy

=

cost of  $s_{t_0} \rightsquigarrow_X^* s'$  is **polynomial** in  $|t_0|$  and  $n$ .

# Recipe for Proving that a Strategy is Reasonable

$\rightsquigarrow$  is a reasonable strategy

=  
cost of  $s_{t_0} \rightsquigarrow_X^* s'$  is polynomial in  $|t_0|$  and  $n$ .

3 ingredients:

1. Reasonable **micro steps**:  
the **cost** of each  $\rightsquigarrow_X$  steps is polynomially bounded.  
 $\Rightarrow \rightsquigarrow_X$  is reasonable.
2. Reasonable **simulation**:  
**number** of  $\rightsquigarrow_X$  steps reasonable in the number of  $\beta \rightsquigarrow$ -steps.  
 $\Rightarrow \rightsquigarrow$  is reasonable.
3. Reasonable **representations**:  
terms with sharing can be compared without unsharing them.

# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

**Unfolding and Reasonable Representations**

Efficiency and Reasonable Cost Models

## Explicit Substitutions & Unfolding

Our implementation scheme for an evaluation  $t_0 \rightsquigarrow^n u$ :

**Input:** a  $\lambda$ -term  $t_0$ ;

**Output:** a compact representation  $r$  of the result  $u$ .

**Compact representation** = a term with **Explicit Substitutions**.

**Real normal form** obtained via decoding / **unfolding** ES.

**Unfolding:**  $r$  is a shared representation of the  $\lambda$ -term  $r \downarrow$ :

$$\begin{array}{ll} x \downarrow & := x; & (rs) \downarrow & := r \downarrow s \downarrow; \\ (\lambda x.r) \downarrow & := \lambda x.r \downarrow; & r[x \leftarrow s] \downarrow & := r \downarrow \{x \leftarrow s \downarrow\}. \end{array}$$

**Example:**

$$\begin{aligned} (xx)[x \leftarrow yy][y \leftarrow zz] \downarrow &= (xx)\{x \leftarrow yy\}\{y \leftarrow zz\} \\ &= (yyyy)\{y \leftarrow zz\} \\ &= zzzzzzzz \end{aligned}$$

# ES are a Reasonable Representation

Our implementation scheme for an evaluation  $t_0 \rightsquigarrow^n u$ :

**Input:** a  $\lambda$ -term  $t_0$ ;

**Output:** a compact representation  $r$  of the result  $r\downarrow = u$ .

**Size explosion:**  $r\downarrow$  can be **exponentially** bigger than  $r$ .

Are we **hiding** size explosion in  $r\downarrow$ ?

**NO!** ES are a **reasonable** compact representation:

Theorem (Accattoli & Dal Lago 2012)

$r\downarrow = s\downarrow$  can be checked in time **polynomial** in  $|r| + |s|$ .

Grabmeyer & Rochel, ICFP '14:  $r\downarrow = s\downarrow$  is **pseudo-linear**.

# Recipe for Proving that a Strategy is Reasonable

3 ingredients:

1. Reasonable **micro steps**;
2. Reasonable **simulation**;
3. Reasonable **representations** (just **treated**).

**Point 3** has to be proved only once.

**Points 1** and **2** depend very much on the  $\lambda$ -dialect.

## Literature: Closed Cases

In the **Closed**  $\lambda$ -Calculus (*i.e.* weak evaluation + closed terms):

The number of  $\beta$ -steps is a **reasonable** cost model.

Ordinary **abstract machines** (*e.g.* KAM) are enough.

Both **reasonable steps** and **reasonable simulation** are easy.

This is **enough** for the effective Church-Turing thesis.

# Literature: Closed Cases

3 independent proofs for the Closed  $\lambda$ -Calculus:

Blelloch & Greiner '96;

(CbV)

Sands & Gustavsson & Moran '02;

(CbV and CbN)

Dal Lago & Martini '09.

(CbV and CbN)

Decomposed and refined by the Accattoli & coauthors in '14.

(CbV, CbN, CbNeed)



# Literature: Strong Case

**Main result** on cost models (Accattoli & Dal Lago, CSL-LICS '14):

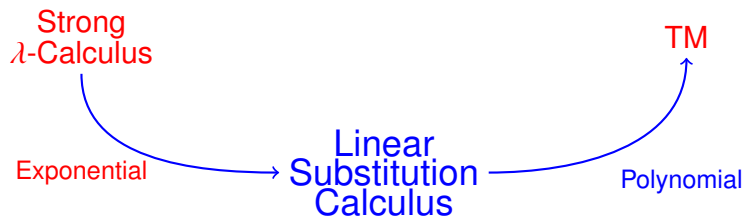
The leftmost strategy is **reasonable**.

**Reasonable steps** is **easy**.

**Reasonable simulation** is **hard**.

Ordinary abstract machines do **not** work.

# Schema of the Solution



## Literature: Strong Case

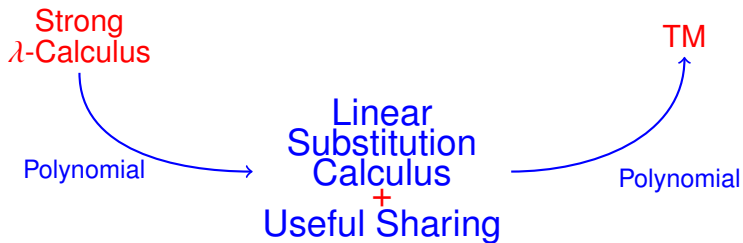
Reasonable simulation **requires** an additional layer of sharing.

A sophisticated layer called **useful sharing**.

First proof using **LSC**, by Accattoli and Dal Lago (2014).

Second proof using an **abstract machine**, by Accattoli (2016).

# Schema of the Solutions



# Outline

Introducing  $\lambda$ -Calculi

The Structure of the Problem

The Deterministic  $\lambda$ -Calculus

Introducing Size Explosion

Size Explosion is Everywhere

$\lambda$ -Calculi are Reasonable

Unfolding and Reasonable Representations

**Efficiency and Reasonable Cost Models**

# Literature: Strong Optimal Cases

The sequential optimal strategy is **non recursive**.

**Subtlety**: its length can still be a reasonable cost model.

(Is it? Open problem)

Lévy's parallel optimal strategy is **recursive** and **unreasonable**.

(Asperti & Mairson 1998)

**Intuition**:

too many sequential steps merged in a single parallel one.

**Open Problem**:

is Lévy's strategy **efficient**? And what does that mean exactly?

# Reasonable vs Efficient

Efficiency = **comparative** property.

Reasonable = property of a strategy, in **isolation**.

Reasonable strategy = implementable with **negligible overhead**.

Being reasonable is **not** about efficiency.

Yet, length is an **efficiency metric** only for reasonable strategies.

Reasonable  $\Rightarrow$  **simplified** study of efficiency.

## Reasonable vs Efficient

Leftmost evaluation is **desperately inefficient**.

Proof that is reasonable requires **useful sharing**.

Useful sharing is a general, **modular** technique.

Useful sharing applies to **more efficient** strategies (CbV / CbNeed).

Reasonable  $\Rightarrow$  **more efficient** implementation techniques.



THANKS!